## Shore Island Post, Isabela

December 20, 2022.



Centroid coordinates: 18.50895° N 67.02893° W

**3D map** Shore Island Post, Isabela



2D map



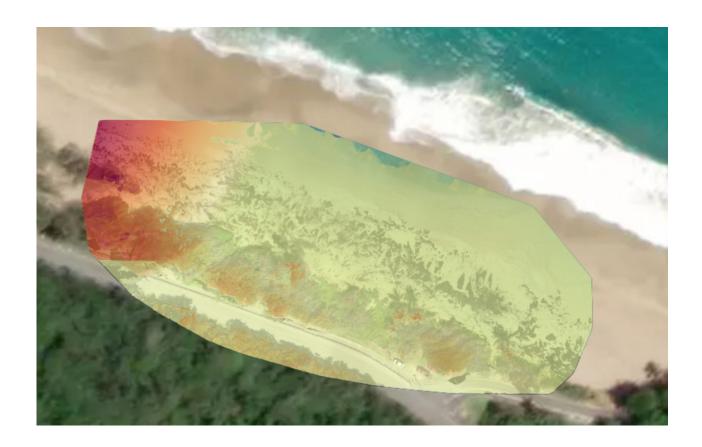
Total area of site = 1.49051 ha

## Beach length (m) Shore Island Post, Isabela



**Beach length** = 178.329 m

## **Density surface model** Shore Island Post, Isabela



# **Area of the beach**Shore Island Post, Isabela



Area of the beach = 8,691.91 m<sup>2</sup>

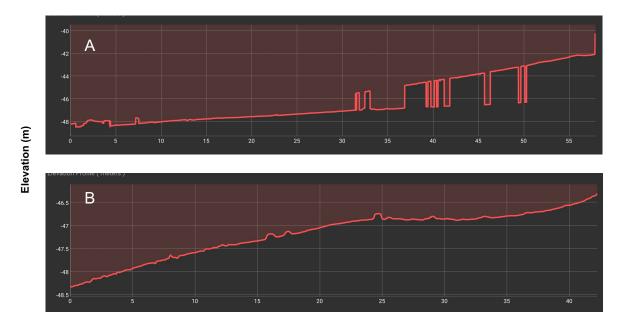
## Beach volume Shore Island Post, Isabela



Cut = 0.00 m<sup>3</sup> Fill = -385,656 m<sup>3</sup> Volume Dif. = -385,656 m<sup>3</sup>

## **Beach elevation** Shore Island Post, Isabela





Distance from shore (m)

## **Site elevation (m)** Shore Island Post, Isabela





Distance from shore (m)

## **Dune height (m)** Shore Island Post, Isabela



## Dune height

**A** = 3.273 m

B = 5.084 m

**C** = 5.118 m

**D** = 6.813 m

**E** = 4.985 m

## **Dune width (m)** Shore Island Post, Isabela



### **Dune width**

**A** = 17.469 m

B = 21.505 m

**C** = 17.474 m

D = 18.937 m

**E** = 10.388 m

## Area and perimeter of dune

Shore Island Post, Isabela



### A- Area and perimeter of dune

**2D** area =  $3,219.18 \text{ m}^2$ 

**3D area** =  $3,381.87 \text{ m}^2$ 

**2D perimeter** = 373.24 m

3D perimeter = 383.514 m

Elevation difference = 17.232 m

### B- Area and perimeter of dune

**2D area** = 204.343 m<sup>2</sup>

**3D area** =  $204.343 \text{ m}^2$ 

**2D perimeter** = 71.344 m

3D perimeter = 71.344 m

**Elevation difference** = 0.00 m

## **Volume of dune** Shore Island Post, Isabela



Base surface	\ Triangulated
Cut volume	•
Cut error	5,190.03 m³ 150.946 m³
Fill volume Fill error	-792.682 m³ 54.7607 m³
Volume difference	4,397.35 m³

В	
Base surface	Triangulated
Cut volume	0.00 m³
Cut error	0.00 m³
Fill volume	-8,987.14 m³
Fill error	3.25663 m <sup>3</sup>
Volume difference	-8,987.14 m³

**Shoreline**Shore Island Post, Isabela



**Shoreline length** = 180.7 m

## **Shoreline geolocation**

Shore Island Post, Isabela



### Shoreline markers

**A** = 18.50937° N 67.02922° W **B** = 18.50919° N 67.02902° W **C** = 18.50916° N 67.02874° W **D** = 18.50905° N 67.02849° W **E** = 18.50900° N 67.02821° W

### **Shoreline extension**

Shore Island Post, Isabela



### Shoreline extension

**A** = 13.173 m

**B** = 22.939 m

**C** = 19.911 m

**D** = 10.189 m

## **Shoreline position**

Shore Island Post, Isabela



### Shoreline position

**A** =

**B** = 64.927 m

**C** = 49.76 m

**D** = 19.704 m

## Area of dune breaches

Shore Island Post, Isabela



### Area of dune breaches

**Breach A**= 3,219.18 m<sup>2</sup> **Breach B**= 204.343 m<sup>2</sup>

## **Quality Report**

Dix4n

Generated with Pix4Denterprise version 4.8.2 Preview



Important: Click on the different icons for:

- ? Help to analyze the results in the Quality Report
- Additional information about the sections



Click <u>here</u> for additional tips to analyze the Quality Report

### Summary

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Project	196270-Project-2022-12-20T18:37:37.579Z
Processed	2022-12-20 19:23:58
Camera Model Name(s)	FC6310R_8.8_5472x3648 (RGB)
Average Ground Sampling Distance (GSD)	1.06 cm / 0.42 in
Area Covered	0.015 km <sup>2</sup> / 1.4849 ha / 0.01 sq. mi. / 3.6712 acres
Time for Initial Processing (without report)	36m:53s

### **Quality Check**

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? Images	median of 47409 keypoints per image	<b>O</b>
? Dataset	193 out of 214 images calibrated (90%), all images enabled, 4 blocks	<u> </u>
? Camera Optimization	0.09% relative difference between initial and optimized internal camera parameters	<b>O</b>
Matching	median of 17992.6 matches per calibrated image	<b>O</b>
@ Georeferencing	yes, no 3D GCP	Δ







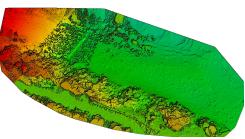


Figure 1: Orthomosaic and the corresponding sparse Digital Surface Model (DSM) before densification.

## **Calibration Details**

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Number of Calibrated Images	193 out of 214
Number of Geolocated Images	214 out of 214

Initial Image Positions

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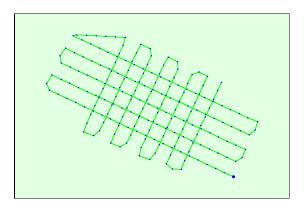
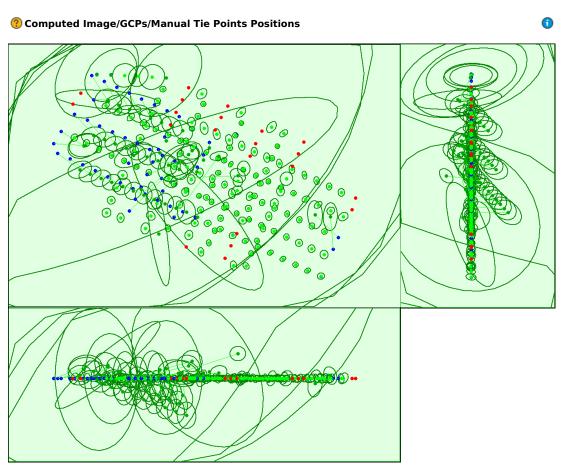


Figure 2: Top view of the initial image position. The green line follows the position of the images in time starting from the large blue dot.



Uncertainty ellipses 1000x magnified

Figure 3: Offset between initial (blue dots) and computed (green dots) image positions as well as the offset between the GCPs initial positions (blue crosses) and their computed positions (green crosses) in the top-view (XY plane), front-view (XZ plane), and side-view (YZ plane). Red dots indicate disabled or uncalibrated images. Dark green ellipses indicate the absolute position uncertainty of the bundle block adjustment result.

### Absolute camera position and orientation uncertainties

	X [m]	Y [m]	Z [m]	Omega [degree]	Phi [degree]	Kappa [degree]
Mean	0.006	0.005	0.006	0.015	0.011	0.009
Sigma	0.018	0.017	0.015	0.039	0.025	0.020



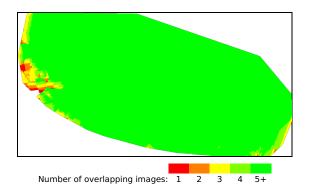


Figure 4: Number of overlapping images computed for each pixel of the orthomosaic.

Red and yellow areas indicate low overlap for which poor results may be generated. Green areas indicate an overlap of over 5 images for every pixel. Good quality results will be generated as long as the number of keypoint matches is also sufficient for these areas (see Figure 5 for keypoint matches).

## **Bundle Block Adjustment Details**

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Number of 2D Keypoint Observations for Bundle Block Adjustment	
Number of 3D Points for Bundle Block Adjustment	907327
Mean Reprojection Error [pixels]	0.168

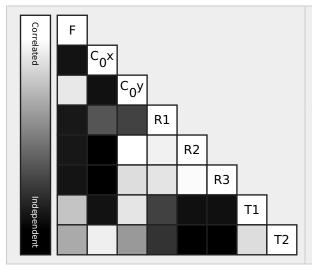
#### Internal Camera Parameters

**☐** FC6310R\_8.8\_5472x3648 (RGB). Sensor Dimensions: 12.833 [mm] x 8.556 [mm]

### **(1)**

### EXIF ID: FC6310R\_8.8\_5472x3648

	Focal Length	Principal Point x	Principal Point y	R1	R2	R3	T1	T2
Initial Values	3658.300 [pixel] 8.580 [mm]	2722.500 [pixel] 6.385 [mm]	1835.100 [pixel] 4.304 [mm]	-0.269	0.112	-0.033	0.000	-0.001
Optimized Values	3654.677 [pixel] 8.571 [mm]	2737.192 [pixel] 6.419 [mm]	1824.272 [pixel] 4.278 [mm]	0.001	-0.016	0.015	-0.000	-0.000
Uncertainties (Sigma)	0.154 [pixel] 0.000 [mm]	0.078 [pixel] 0.000 [mm]	0.166 [pixel] 0.000 [mm]	0.000	0.000	0.000	0.000	0.000



The correlation between camera internal parameters determined by the bundle adjustment. White indicates a full correlation between the parameters, ie. any change in one can be fully compensated by the other. Black indicates that the parameter is completely independent, and is not affected by other parameters.

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The number of Automatic Tie Points (ATPs) per pixel, averaged over all images of the camera model, is color coded between black and white. White indicates that, on average, more than 16 ATPs have been extracted at the pixel location. Black indicates that, on average, 0 ATPs have been extracted at the pixel location. Click on the image to the see the average direction and magnitude of the re-projection error for each pixel. Note that the vectors are scaled for better visualization. The scale bar indicates the magnitude of 1 pixel error.

### ② 2D Keypoints Table



	Number of 2D Keypoints per Image	Number of Matched 2D Keypoints per Image
Median	47409	17993
Min	21120	180
Max	78630	34418
Mean	49057	16751

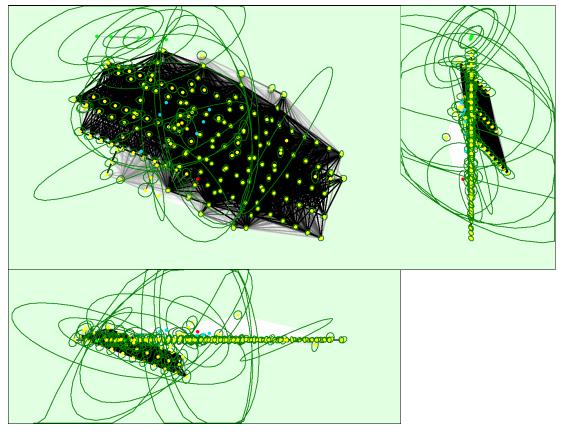
### ? 3D Points from 2D Keypoint Matches



	Number of 3D Points Observed
In 2 Images	525942
In 3 Images	150787
In 4 Images	72126
In 5 Images	42249
In 6 Images	27545
In 7 Images	19001
In 8 Images	13530
In 9 Images	10172
In 10 Images	7893
In 11 Images	6226
In 12 Images	5037
In 13 Images	4054
In 14 Images	3270
In 15 Images	2805
In 16 Images	2405
In 17 Images	1908
In 18 Images	1681
In 19 Images	1356
In 20 Images	1199
In 21 Images	990
In 22 Images	871
In 23 Images	758
In 24 Images	641
In 25 Images	585
In 26 Images	492
In 27 Images	408
In 28 Images	391
In 29 Images	331
In 30 Images	303
In 31 Images	237
In 32 Images	235
In 33 Images	204
In 34 Images	191
In 35 Images	155
In 36 Images	164
In 37 Images	146
In 38 Images	134
In 39 Images	119
In 40 Images	99

In 41 Images	73
In 42 Images	78
In 43 Images	73
In 44 Images	60
In 45 Images	60
In 46 Images	40
In 47 Images	51
In 48 Images	39
In 49 Images	39
In 50 Images	33
In 51 Images	29
In 52 Images	20
In 53 Images	19
In 54 Images	12
In 55 Images	12
In 56 Images	3
In 57 Images	12
In 58 Images	9
In 59 Images	6
In 60 Images	2
In 61 Images	6
In 62 Images	5
In 63 Images	3
In 64 Images	1
In 65 Images	2

### ② 2D Keypoint Matches



Uncertainty ellipses 500x magnified

Number of matches

#### 25 222 444 666 888 1111 1333 1555 1777 2000

Figure 5: Computed image positions with links between matched images. The darkness of the links indicates the number of matched 2D keypoints between the images. Bright links indicate weak links and require manual tie points or more images. Dark green ellipses indicate the relative camera position uncertainty of the bundle block adjustment result.

### Relative camera position and orientation uncertainties

**(1** 

	X [m]	Y [m]	Z [m]	Omega [degree]	Phi [degree]	Kappa [degree]
Mean	0.007	0.006	0.007	0.023	0.013	0.012
Sigma	0.013	0.014	0.016	0.065	0.029	0.028

### **Geolocation Details**

**(1)** 

#### Absolute Geolocation Variance

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Min Error [m]	Max Error [m]	Geolocation Error X [%]	Geolocation Error Y [%]	Geolocation Error Z [%]
-	-0.09	0.00	0.00	0.71
-0.09	-0.07	0.00	0.00	0.71
-0.07	-0.05	0.00	0.00	0.00
-0.05	-0.03	0.00	0.00	3.55
-0.03	-0.02	0.00	1.42	10.64
-0.02	0.00	53.90	48.94	37.59
0.00	0.02	43.97	49.65	26.24
0.02	0.03	2.13	0.00	17.02
0.03	0.05	0.00	0.00	2.84
0.05	0.07	0.00	0.00	0.00
0.07	0.09	0.00	0.00	0.00
0.09	-	0.00	0.00	0.71
Mean [m]		0.000127	-0.000018	-0.000556
Sigma [m]		0.007027	0.006351	0.022423
RMS Error [m]		0.007028	0.006351	0.022430

Min Error and Max Error represent geolocation error intervals between -1.5 and 1.5 times the maximum accuracy of all the images. Columns X, Y, Z show the percentage of images with geolocation errors within the predefined error intervals. The geolocation error is the difference between the initial and computed image positions. Note that the image geolocation errors do not correspond to the accuracy of the observed 3D points.

#### Relative Geolocation Variance

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Relative Geolocation Error	Images X [%]	Images Y [%]	Images Z [%]
[-1.00, 1.00]	95.04	97.16	84.40
[-2.00, 2.00]	100.00	100.00	97.87
[-3.00, 3.00]	100.00	100.00	100.00
Mean of Geolocation Accuracy [m]	0.013929	0.013929	0.029715
Sigma of Geolocation Accuracy [m]	0.003403	0.003403	0.008002

Images X, Y, Z represent the percentage of images with a relative geolocation error in X, Y, Z.

Geolocation Orientational Variance	RMS [degree]
Omega	0.739
Phi	0.556
Карра	3.096

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ystem Information				
Hardware	CPU: Intel(R) Xeon(R) Platinum 8223CL CPU @ 3.00GHz RAM: 69GB GPU: no info (Driver: unknown)			
Operating System	Linux 5.15.0-1026-aws x86_64			
oordinate Systems				
Image Coordinate System		WGS 84		
Output Coordinate System		WGS 84 / UTM zone 19N		
rocessing Options  Detected Template				
Keypoints Image Scale		Full, Image Scale: 1		
Advanced: Matching Image Pairs	5	Aerial Grid or Corridor		
Advanced: Matching Strategy		Use Geometrically Verified Matching: no		
Advanced: Keypoint Extraction		Targeted Number of Keypoints: Automatic		
		Calibration Method: Standard Internal Parameters Optimization: All		
Advanced: Calibration  Point Cloud De	ensificatio	External Parameters Optimization: All Rematch: Auto, yes		
Point Cloud De	ensificatio	External Parameters Optimization: All Rematch: Auto, yes		
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DSM, Orthomosaic and Index Details

### **Processing Options**

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DSM and Orthomosaic Resolution	1 x GSD (1.06 [cm/pixel])
DSM Filters	Noise Filtering: yes Surface Smoothing: yes, Type: Sharp
Raster DSM	Generated: yes Method: Inverse Distance Weighting Merge Tiles: yes
Orthomosaic	Generated: yes Merge Tiles: yes GeoTIFF Without Transparency: no Google Maps Tiles and KML: no
Time for DSM Generation	03m:00s
Time for Orthomosaic Generation	09m:42s
Time for DTM Generation	00s
Time for Contour Lines Generation	00s
Time for Reflectance Map Generation	00s
Time for Index Map Generation	00s

## Shore Island Post, Isabela

